The Atiyah-Bott Localization Formula

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The Atiyah-Bott Localization Formula in Enumerative Geometry

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Outline

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- Equivariant Cohomology in Algebraic Geometry (David Anderson and William Fulton)
- 3264 and All That (David Eisenbud and Joe Harris)

Definition

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$$\mathbb{E}G \times^G X \coloneqq \mathbb{E}G \times X / (e \cdot g, x) \sim (e, g \cdot x).$$

Definition

The equivariant cohomology of X with respect to G is

$$H^*_G(X) \coloneqq H^*(\mathbb{E}G \times^G X; \mathbb{Z}).$$

Special case: If X is a point, then $H^*_G(\mathsf{pt}) = H^*(\mathbb{B}G)$, where $\mathbb{B}G = \mathbb{E}G/G$ is the classifying space of G. Write $\Lambda_G = H^*_G(\mathsf{pt})$

For a Torus...

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Example

Consider a torus $T=(\mathbb{C}^*)^n.$ Then $\mathbb{E} T=(\mathbb{C}^\infty-0)^n$ and $\mathbb{B} T=(\mathbb{P}^\infty)^n,$ and

$$\Lambda_T = \mathbb{Z}[t_1, \ldots, t_n],$$

where $t_i = c_1(\mathscr{O}_{\mathbb{P}^\infty}(-1))$ is the tautological line bundle on the *i*-th factor of $(\mathbb{P}^\infty)^n$.

Equivariant Chern Class

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A *G*-equivariant vector bundle produces an ordinary vector bundle $\mathbb{E} \times^G E \to \mathbb{E} \times^G X$.

Definition

Define the equivariant Chern class of E as

$$c_k^G(E) \coloneqq c_k(\mathbb{E} \times^G E) \in H^{2k}_G(X)$$

Equivariant Fundamental Class

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Definition

Define the equivariant fundamental class of V as

$$[V]^G = [\mathbb{E} \times^G V] \in H^{2d}_G(X).$$

Localization

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Solving Steiner's Problem Torus action Helpful diagrams Tangent weights Restrictions of classes Last steps From now on, suppose X is a nonsingular projective T-variety with finitely many fixed points.

Theorem (Atiyah-Bott localization formula)

For any class $\alpha \in H^*_T X$, we have

$$\int_{X} \alpha = \sum_{p \in X^{T}} \frac{\alpha|_{p}}{c_{top}^{T}(T_{p}X)}$$

An Important Example

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■ Consider T = (C*)ⁿ acting on Pⁿ⁻¹ by weights t₁,...,t_n, i.e.

$$w \cdot [z_1, \dots, z_n] = [t_1(w)z_1, \dots, t_n(w)z_n]$$

where $t_i \in \text{Hom}(T, C^*)$. The fixed points are $p_i = [0, \dots, 0, 1, 0, \dots, 0]$ and the weights on $T_{p_i} \mathbb{P}^{n-1}$ are $t_j - t_i$ for $j \neq i$. Then Then

$$c_{n-1}^{T}(T_{p_i}\mathbb{P}^{n-1}) = \prod_{j \neq i} (t_j - t_i).$$

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Conics are defined by homogeneous equations $aX^2+bY^2+cZ^2+dXY+eYZ+fXZ=0 \mbox{ modulo scalar multiplication}.$

Taking the coefficients, the moduli space of conics is $\mathbb{P}(V)$, where $V = \operatorname{Sym}^2 \mathbb{C}^3$.

Then V is 6-dimensional, so $\mathbb{P}(V) \cong \mathbb{P}^5$.

For a fixed conic C, the set of conics tangent to C forms a sextic hypersurface $Z_C \subset \mathbb{P}(V)$. So $[Z_C] = 6H$.

Solution Setup

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Solving Steiner's Problem Torus action Helpful diagrams Tangent weights Restrictions of classes Last steps Steiner's claim: by Bezout's Theorem,

$$\int_{\mathbb{P}(V)} [Z_{C_1}] \cdots [Z_{C_5}] = \int_{\mathbb{P}(V)} (6H)^5 = 7776.$$

Unfortunately, this is **incorrect**.

Indeed, every double line is tangent to any conic, so $\bigcap Z_{C_i}$ contains the Veronese surface $S \subset \mathbb{P}^5$.

(S corresponds to the set of double lines in \mathbb{P}^2 .)

But $S \cong \mathbb{P}^2$, so $\bigcap Z_{C_i}$ is not transverse.

Instead, we need to modify the moduli space by blowing up $\mathbb{P}(V)$ along the Veronese surface S to get the space of complete conics $\mathscr{C} = \operatorname{Bl}_S \mathbb{P}(V)$.

Complete Conics

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$$C^* \coloneqq \{l \subset \mathbb{P}^2 : l \text{ is tangent to } C\}.$$

For singular conics, the dual is the closure of the tangents at nonsingular points.

Mapping [C] to $[C^*]$ gives a rational map $\mathbb{P}(V) \dashrightarrow \mathbb{P}(V^*)$ that is regular on $\mathbb{P}(V) \setminus S$.

Complete Conics (cont.)

The Atiyah-Bott Localization Formula

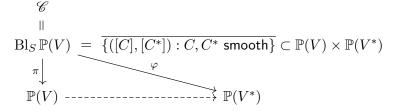
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Solving Steiner's Problem Torus action Helpful diagrams Tangent weights Restrictions of classes Last steps Its indeterminacy is resolved by blowing up $\mathbb{P}(V)$ at S, and we get



Characterization of Complete Conics

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Solving Steiner's Problem Torus action Helpful diagrams Tangent weights Restrictions of classes Last steps One can show that $\mathscr C$ consists of four types of figures in $\mathbb P^2$: **1** nonsingular conics

2 unions of two lines

3 lines with two marked points

4 lines with one marked point

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Torus action Helpful diagrams Tangent weights Restrictions of classes Last steps Let $\widetilde{Z_C}$ be the proper transform of Z_C .

Given five general conics C_1, \ldots, C_5 , one can prove that $\widetilde{Z_{C_i}}$ intersect transversally.

For $p \in \mathbb{P}^2$, define hyperplane $\Sigma_p \subset \mathbb{P}(V)$ of conics containing p.

For $l \in (\mathbb{P}^2)^*$, define hyperplane $\Theta_l \subset \mathbb{P}(V^*)$ of conics tangent to l.

Let σ_p,τ_l be the proper transforms. Non-equivariantly, their classes are independent of p and l.

One can show that $\widetilde{Z} = 2\sigma + 2\tau$ in $H^*\mathscr{C}$.

The Correct Integral

The Atiyah-Bott Localization Formula

Solving Steiner's Problem We therefore want to calculate

$$\begin{split} [\widetilde{Z}]^5 &= \int_{\mathscr{C}} (2\sigma + 2\tau)^5 \\ &= 32 \bigg(\int \sigma^5 + 5 \int \sigma^4 \tau + 10 \int \sigma^3 \tau^2 \\ &+ 10 \int \sigma^2 \tau^3 + 5 \int \sigma \tau^4 + \int \tau^5 \bigg). \end{split}$$

Note that

•
$$\int \sigma^i \tau^{5-i} = \int \sigma^{5-i} \tau^i$$
 by symmetry;
• $\int \sigma^5 = 1.$

So we only need to calculate $\int \sigma^4 \tau$ and $\int \sigma^3 \tau^2$.

Constructing the Torus Action

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Solving Steiner's Problem Torus action Helpful diagrams Tangent weights Restrictions of classes Last steps Let $T = (\mathbb{C}^*)^3$ act on \mathbb{P}^2 with weights t_1, t_2, t_3 . The induced action on $V = \text{Sym}^2 \mathbb{C}^3$ has weights

 $2t_1, 2t_2, 2t_3, t_1 + t_2, t_2 + t_3, t_1 + t_3$

corresponding to the basis

 $X^2, Y^2, Z^2, XY, YZ, XZ.$

The tangent spaces to $\mathbb{P}(V)$ at X^2 and XY have weights

$$T_{X^2}\mathbb{P}(V): \{2(t_2-t_1), 2(t_3-t_1), t_2-t_1, t_2+t_3-2t_1, t_3-t_1\}$$

$$T_{XY}\mathbb{P}(V): \{t_1-t_2, t_2-t_1, 2t_3-t_1-t_2, t_3-t_1, t_3-t_2\}.$$

Fixed Points of the Torus Action

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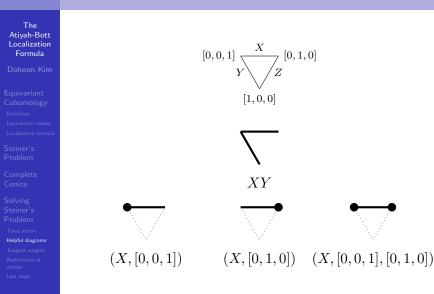
Solving Steiner's Problem Torus action Helpful diagrams Tangent weights Restrictions of classes Last steps Recall the localization formula:

$$\int_X \alpha = \sum_{p \in X^T} \frac{\alpha|_p}{c_{\mathsf{top}}^T(T_p X)}.$$

To use localization, we need the **fixed points** of \mathscr{C} and their **tangent weights.** Note that $\pi : \mathscr{C} \to \mathbb{P}(V)$ maps fixed points to fixed points.

- **1** Over XY, π is an isomorphism, so the corresponding fixed point in \mathscr{C} is a pair of lines.
- **2** Over X^2 , we need to add data of one or two points (which also need to be *T*-invariant).

Helpful Diagrams



Tangent Weights of a Blowup

The Atiyah-Bott Localization Formula

Theorem

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Restrictions o classes Last steps Let X be a smooth T-variety and $S \subset X$ a smooth T-invariant subvariety. Let $\widetilde{X} = \operatorname{Bl}_S X$ be the blowup, $N = N_{S/X}$ the normal bundle, and $E = \mathbb{P}(N) \to S$ the exceptional divisor. Take $x \in E$, which corresponds to a line $L \subset N_s$, i.e. $L = \mathscr{O}(-1)|_x$, where $E \to S$ maps x to s. Then

 $T_x \widetilde{X} = T_x E \oplus L$ = Hom(L, N_s/L) \oplus T_sS \oplus L.

Using this, let us calculate the weights at $T \leftarrow \mathscr{C}$.

Calculating the Tangent Weights (1)

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Restrictions of classes Last steps Recall that ∇ projects to $X^2 \in S \subset \mathbb{P}(V)$ and that $T_{X^2}\mathbb{P}(V)$ has weights

$$T_{X^2}\mathbb{P}(V): \{2(t_2-t_1), 2(t_3-t_1), t_2-t_1, t_2+t_3-2t_1, t_3-t_1\}.$$

From the action of T on $S \cong \mathbb{P}^2$, the tangent space $T_{X^2}S$ has weights

$$T_{X^2}S: \{t_2 - t_1, t_3 - t_1\}.$$

So the normal weights to S at X^2 are

$$N_{X^2}S: \{2(t_2-t_1), 2(t_3-t_1), t_2+t_3-2t_1\}.$$

Calculating the Tangent Weights (2)

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Restrictions of classes Last steps Each weight corresponds to a T-invariant line $L \subset N$, hence a T-fixed point in E.

$$2(t_2 - t_1) \leftrightarrow \overleftarrow{\bigtriangledown}$$
$$2(t_1 - t_2) \leftrightarrow \overleftarrow{\lor}$$
$$t_2 + t_3 - 2t_1 \leftrightarrow \overleftarrow{\lor}$$

Take
$$L \leftrightarrow 2(t_2 - t_1) \leftrightarrow \bullet$$

Calculating the Tangent Weights (3)

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Classes Last steps

We have

$$T = E: \{t_2 - t_1, t_3 - t_1\} \\ \cup \{(t_2 + t_3 - 2t_1) - 2(t_2 - t_1), 2(t_3 - t_1) - 2(t_2 - t_1)\}$$

and so

$$T \leftarrow \mathscr{C}: \{t_2 - t_1, t_3 - t_1, t_3 - t_2, 2(t_3 - t_2)\} \cup \{2(t_2 - t_1)\}.$$

Similar calculations for $\overline{\bigtriangledown}$ and $\overline{\frown}$.

The Hyperplane Classes

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Solving Steiner's Problem Torus action Helpful diagrams Tangent weights Restrictions of classes Recall the localization formula:

$$\int_X \alpha = \sum_{p \in X^T} \frac{\alpha|_p}{c_{\mathsf{top}}^T(T_p X)}.$$

We need the restrictions of σ_p and τ_l at each fixed point. One can show that

$$\sigma_p = \pi^* \Sigma_p,$$

$$\tau_l = \varphi^* \Sigma_l^*,$$

$$[\Sigma_p]^T = c_1^T (\mathscr{O}(1) \otimes \mathbb{C}_{2t_1})$$

Restrictions of the Classes at the Fixed Points

The Atiyah-Bott Localization Formula

So for
$$p = \bullet$$
 ,

Restrictions of classes

So for
$$p = \bullet$$
 ,

$$\sigma_{\underbrace{\bullet}} |_{\underbrace{\bullet}} = \sigma_{\underbrace{\bullet}} |_{\underbrace{\bullet}} = \sigma_{\underbrace{\bullet}} |_{\underbrace{\bullet}} = \Sigma_{\underbrace{\bullet}} |_{\overleftarrow{\bullet}} = 0,$$

$$\sigma_{\underbrace{\bullet}} |_{\overleftarrow{\bullet}} = \Sigma_{\underbrace{\bullet}} |_{\overleftarrow{\bullet}} = t_1 - t_2,$$

etc.

and for l = N,

$$\tau_{\chi\gamma}|_{\overrightarrow{\gamma}} = \tau_{\chi\gamma}|_{\overrightarrow{\gamma}} = \tau_{\chi\gamma}|_{\overrightarrow{\gamma}} = 0,$$

$$\tau_{\chi\gamma}|_{\overrightarrow{\gamma}} = t_3 - t_2,$$

etc.

Calculating the Integrals

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Last steps

To calculate
$$\int_{\mathscr{C}} \sigma^4 \tau$$
, consider the class
 $\alpha = (\sigma \gamma)^2 \sigma \sigma \sigma \sigma \sigma \tau \gamma$

Then α_{∇} and α_{∇} are the only nonzero restrictions. So $\int_{\mathscr{C}} \sigma^4 \tau = \int_{\mathscr{C}} \alpha$ $= \frac{\alpha|_{\nabla}}{c_{\mathrm{top}}^T(T_{\nabla}\mathscr{C})} + \frac{\alpha|_{\nabla}}{c_{\mathrm{top}}^T(T_{\nabla}\mathscr{C})}$ $= \frac{\alpha|_{\nabla}}{\prod\{\text{weights of } T_{\nabla}\mathscr{C})\}} + \frac{\alpha|_{\nabla}}{\prod\{\text{weights of } T_{\nabla}\mathscr{C})\}}$ $= \cdot \cdot \cdot$ = 2.

Final Solution

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Last steps

Do a similar calculation for $\sigma^3 \tau^2$ to get $\int_{\mathscr{C}} \sigma^3 \tau^2 = 4$. We then have

$$\begin{split} \int_{\mathscr{C}} [\widetilde{Z}]^5 &= \int_{\mathscr{C}} (2\sigma + 2\tau)^5 \\ &= 32 \bigg(\int \sigma^5 + 5 \int \sigma^4 \tau + 10 \int \sigma^3 \tau^2 \\ &+ 10 \int \sigma^2 \tau^3 + 5 \int \sigma \tau^4 + \int \tau^5 \bigg) \\ &= 32(1 + 5 \cdot 2 + 10 \cdot 4 + 10 \cdot 4 + 5 \cdot 2 + 1) \\ &= 3264. \end{split}$$

This is the correct solution to Steiner's problem.